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	<b>Filing Date</b>		2006-04-26	
	<b>First Named Inventor</b>	Moshe Shoham		
	<b>Art Unit</b>	2121		
	<b>Examiner Name</b>	Crystal Joy Barnes Bullock		
<b>Attorney Docket Number</b>		0611US-Shoham		

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/CJB/	1	"On the Design of Cable-Suspended Planar Parallel Robots", Abbas Fattah and Sunil K. Agrawal, Journal of Mechanical Design, 1021-1028, vol. 127, Sep. 2005, copyright 2005 by ASME(American Society of Mechanical Engineers) New York, NY	<input type="checkbox"/>
/CJB/	2	"CAT4 (Cable Actuated Truss—4 Degrees of Freedom): A Novel 4 DOF Cable Actuated Parallel Manipulator", Craig Kossowski and Lella Notash, Journal of Robotic Systems 19(12), 605-615 (2002), Copyright 2002 Wiley Periodicals, Inc.	<input type="checkbox"/>
/CJB/	3	"On Design of a Redundant Wire-Driven Parallel robot WARP manipulator", Kiyoshi Maeda, Satoshi Tadokoro, Toshi Takamori, Manfred Hiller, and Richard Verhoeven, Proceedings of the 1599 IEEE International Conference on Robotics & Automation, Detroit, Michigan May 1995	<input type="checkbox"/>
/CJB/	4	"Development of a Large Parallel-Cable Manipulator for the Feed-Supporting System of a Next-Generation Large Radio Telescope", Y. X. Su, B. Y. Duan, R. D. Nan and B. Peng, Journal of Robotic Systems 18(11), 633-643 (2001) © 2001 by John Wiley & Sons, Inc.	<input type="checkbox"/>
/CJB/	5	"Development of an Ultrahigh Speed Robot FALCON using Wire Drive System", S.Kawamura, W.Choe, S.Tanaka, and S.R.Pandian, IEEE international Conference on Robotics and Automation 0-7803-1965-6/95 ©1995 IEEE	<input type="checkbox"/>
/CJB/	6	"On the Inverse Kinematics, Statics, and Fault Tolerance of Cable-Suspended Robots", Rodney G. Roberts, Todd Graham and Thomas Lippitt, Journal of Robotic Systems 15(10), 581-597 (1998) ©1998 by John Wiley & Sons, Inc.	<input type="checkbox"/>
/CJB/	7	"Kinematic Analysis of Planar Parallel Mechanisms Actuated with Cables", Clément M. Gosselin in Guillaume Barrette, Proceedings of the 2000 ASME Design and Engineering Technical Conference 391-399, ©2000, American Society of Mechanical Engineers.	<input type="checkbox"/>
/CJB/	8	"RoboCrane Project: An Advanced Concept for Large Scale Manufacturing", ROGER BOSTELMAN, JAMES ALBUS, NICHOLAS DAGALAKIS, ADAM JACOFF, Robotics and Manufacturing Volume 4 385-390, Asme Press Series, 1992	<input type="checkbox"/>
/CJB/	9	"Concept Paper: Cable-Driven Robots for Use in Hazardous Environments", Andrew T. Riechel, Paul Bosscher, Harvey Lipkin, Imme Ebert-Uphoff, Georgia Institute of Technology, Atlanta, GA	<input type="checkbox"/>
/CJB/	10	"Skycam" Wikipedia, the free encyclopedia, <a href="http://en.wikipedia.org/wiki/Skycam">http://en.wikipedia.org/wiki/Skycam</a> , downloaded July 25, 2008	<input type="checkbox"/>
/CJB/	11	"Translational Planar Cable-Direct-Driven Robots", ROBERT L. WILLIAMS II and PAOLO GALLINA, Journal of Intelligent and Robotic Systems 37: 69-96, 2003. © 2003 Kluwer Academic Publishers.	<input type="checkbox"/>

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/CJB/	12	"Tension Distribution in Tendon Based Stewart Platforms", Richard Verhoeven and Manfred Hiller, Advances in Robot Kinematics 117-124, 2002 Kluwer Academic Publishing.	<input type="checkbox"/>
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Examiner Signature	/Crystal J. Barnes Bullock/	Date Considered	08/29/2008
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